

# On the Decidability of Model-Checking Information Flow Properties

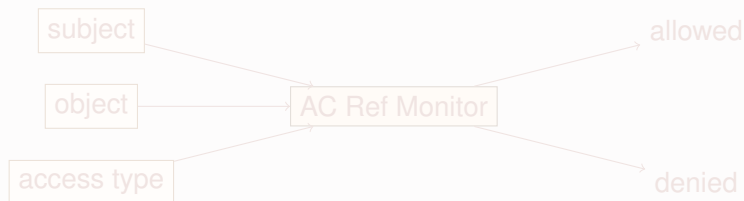
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Joint Work: Deepak D'Souza, Janardhan Kulkarni, Barbara Sprick, Raveendra Holla  
Indian Institute of Science, Bangalore

# Introduction to Software Security

Protecting the confidentiality of information manipulated by computing systems is a long standing yet increasingly important problem. There is little assurance that current computing systems protect data confidentiality and integrity. - Myers (FM for Security)

## Access Control

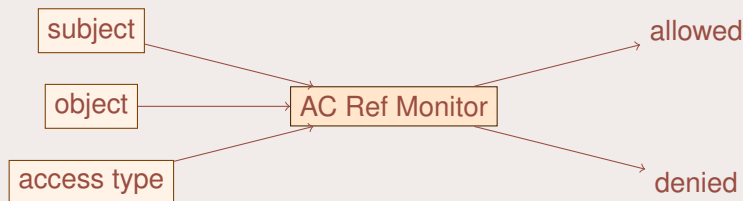


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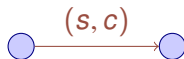
## Access Control



Limitation: Does NOT address end-to-end security.

# Noninterference [GM82]

- Addresses end-to-end security.
- $M = (Q, S, I, O, \delta, o, s_0)$   
 $\delta : Q \times (S \times I) \rightarrow Q,$   
 $o : Q \times S \rightarrow O.$

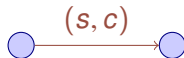


$S_1$  noninterferes with  $S_2$

for all  $s \in S_2$ ,  $o(\hat{\delta}(s_0, w), s) = o(\hat{\delta}(s_0, \text{purge}_{S_1}(w)), s).$

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# Verifying Noninterference = Reachability Check

$$M_{S_1 S_2} = (Q \times Q, S, I, O, \delta', o', (s_0, s_0))$$

$$\delta'((t_1, t_2), (s, a)) = \begin{cases} (\delta(t_1, (s, a)), t_2) & \text{if } s \in S_1 \\ (\delta(t_1, (s, a)), \delta(t_2, (s, a))) & \text{otherwise} \end{cases}$$

$$o'((t_1, t_2), s) = (o(t_1, s), o(t_2, s))$$

$M \models NI$  w.r.t  $S_1, S_2$  [MZ07]

iff for all reachable states  $(t_1, t_2)$  of  $M_{S_1 S_2}$ ,  
 $o'((t_1, t_2), s) = (o_1, o_2) \Rightarrow o_1 = o_2$  for all  $s \in S_2$ .

Decidable for finite state systems.

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# Generalized Noninterference - GNI

Limitation: Non-determinism for interrupts and concurrency.

McCullough'87

$$S_1 \not\sim_{GNI} S_2 \text{ iff } \forall s \in S_2 \forall w \in (S \times I)^* \forall c \in (S_1 \times I), \\ o(\hat{\delta}(s_0, w), s) = o(\hat{\delta}(s_0, w \cdot c), s).$$

- Event Systems:  $(E, I, O, L)$   
 $I, O \subseteq E, I \cap O = \emptyset, L \subseteq E^*$ .
- Assume security levels:  $L \leq H$ .
- $\forall t_1, t_2, t_3 \in E^*$ ,  
 $((t_1.t_2 \in L \wedge t_3 \upharpoonright_{E \setminus (H \cap I)} = t_2 \upharpoonright_{E \setminus (H \cap I)}) \Rightarrow \\ \exists t_4 \in E^*. (t_1.t_4 \in L \wedge t_4 \upharpoonright_{LU(H \cap I)} = t_3 \upharpoonright_{LU(H \cap I)})$



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# Variants of Noninterference

## Noninference (NF) [ZL97]

$$\forall t \in L, t \upharpoonright_L \in L.$$

## Separability (SEP) [McL94]

$$\forall \tau, \tau' \in L, \text{interleaving}(\tau \upharpoonright_H, \tau' \upharpoonright_L) \subseteq L.$$

## Non Deducibility for $UI \subseteq I$ (NDO) [GN88]

$$\forall t_1, t_2 \in L, \forall t \in E^*, \\ (t \upharpoonright_L = t_1 \upharpoonright_L \wedge t \upharpoonright_{HU(L \cap UI)} = t_2 \upharpoonright_{HU(L \cap UI)}) \Rightarrow t \in L.$$

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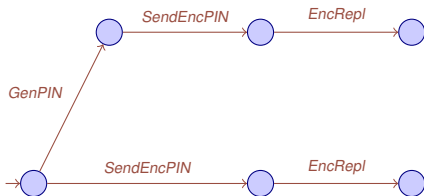
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# An example

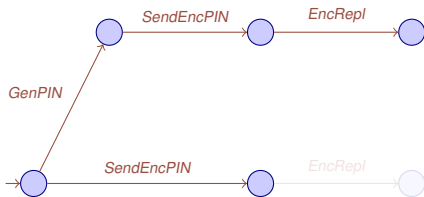
Alice wants to change her PIN.



Noninterference holds. Noninterference violated.

# An example

Alice wants to change her PIN.



Noninterference violated.



# Basic Security Predicates (BSPs) [Mantel'00]

- BSP w.r.t a view =  $(V, N, C)$ .

- BSP  $R$

$$\forall \tau \in L, \Rightarrow \exists \tau', \tau' \upharpoonright_C = \epsilon \wedge \tau \upharpoonright_V = \tau' \upharpoonright_V$$

- BSP  $D$

$$\forall c \in C,$$

$$\forall \alpha \beta \in L \wedge \beta \upharpoonright_C = \epsilon \Rightarrow \exists \alpha' \beta', \alpha' \beta' \in L, \wedge \alpha =_N \alpha' \wedge \beta =_N \beta'$$

- BSP  $I$

$$\forall c \in C,$$

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⋮

13 BSPs

# Information Flow Properties and BSPs

- Let  $\mathcal{H} = (L, \emptyset, H)$ , and  $\mathcal{HI} = (L, H \setminus I, H \cap I)$ .
- $GNI(E) \Leftrightarrow BSD_{\mathcal{HI}}(E) \wedge BSI_{\mathcal{HI}}(E)$ .
- $NDO(E) \Leftrightarrow BSD_{\mathcal{H}}(E) \wedge BSIA_{\mathcal{H}}^{UI}(E)$ .
- $NF(E) \Leftrightarrow R_{\mathcal{H}}(E)$ .
- $SEP(E) \Leftrightarrow BSD_{\mathcal{H}}(E) \wedge BSIA_{\mathcal{H}}^C(E)$ .

⋮

# Model Checking BSPs

- For finite state systems, decidable [DKS'05].
- For pushdown systems (PDS), undecidable.
- Information flow properties for PDS, undecidable [To be submitted]

# Undecidability for PDS

Recall  $NF(E) \Leftrightarrow R_{\mathcal{H}}$ .

Emptiness Problem of Turing Machines to PDS satisfying NF.

Configuration sequence is encoded on  $\{v_1, v_2\}$ .

Given a TM  $M$ , let  $L$  be the prefix closure of  $L_1 \cup L_2$

$L_1 = \{c \cdot enc(\#x_1\#x_2 \cdots x_n\#) \mid x_1 \text{ is a starting configuration, } x_n \text{ is an accepting configuration}\}$

$L_2 = \{enc(\#x_1\#x_2 \cdots x_n\#) \mid x_1 \text{ is a starting configuration, } x_n \text{ is an accepting configuration, exists } i : x_i \rightsquigarrow x_{i+1} \text{ invalid transition}\}$

$L$  satisfies  $NF$  iff  $L(M) = \emptyset$ .

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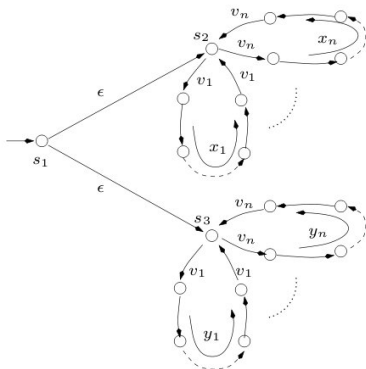
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# Weak Non-Inference

- WNI
  - $\forall \tau \in L, \tau \upharpoonright_C = \epsilon \Rightarrow \exists \tau' \in L, \tau \upharpoonright_V = \tau' \upharpoonright_V \wedge \tau \upharpoonright_C \neq \tau' \upharpoonright_C.$
- Undecidable for finite state systems.
- PCP has a solution iff  $T_P$  does not satisfy WNI.



# Logic Characterization for BSPs

- WNI not definable with BSPs.
- $|V| = |C| = 1$ : decidable for PDS - reduced to PA
- Natural:  $FO_{=}(\cdot, \uparrow)$  is undecidable.



# Summary and Future Work

- Model-Checking noninterference and its variants for PDS is undecidable.
- Attempted logic characterization for BSPs is undecidable.

## For Future

- Decidable Logic characterization of noninterference and its variants.
- Static / Dynamic analysis of programs for refined noninterference.

Thank You